

# SSA vs ANF

Does FP make a better IR?

Does functional  
programming make a  
better intermediate  
representation?

Yes.



“SSA is Functional Programming”

– Appel 1998

# Static Single-Assignment Form

- Invented by imperative compiler writers to make optimisations easier
- Arguments to functions must be atomic (i.e. every sub-expression is named)
- Each variable in a program is assigned only once
- Used by LLVM, GCC, HotSpot, SpiderMonkey, Crankshaft, Dalvik, PyPy, LuaJIT, HHVM, MLton

# Static Single-Assignment Form

```
proc fac(x) {
    r ← 1;
    goto L1;
L1:
    r0 ← ϕ(start : r, L1 : r1);
    x0 ← ϕ(start : x, L1 : x1);
    if x0 then
        r1 ← mul(r0, x0);
        x1 ← sub(x0, 1);
        goto L1;
    else
        ret r0;
}
ret fac(10);
```

p ::= proc x(xs) {b} p | e  
b ::= e | b; x:e | b<sub>1</sub>; x:{b<sub>2</sub>}  
e ::= x ← ϕ(gs); e  
| x ← v; e  
| x ← v(vs); e  
| goto x;  
| ret v;  
| ret v(vs);  
| if v then e<sub>1</sub> else e<sub>2</sub>  
g ::= l:v  
l ::= x | start  
v ::= x | c  
xs ::= x, xs | ε  
vs ::= v, vs | ε  
gs ::= g, gs | ε  
x ::= variable or label  
c ::= constant

# Static Single-Assignment Form

```

proc fac(x) {
    r ← 1;
    goto L1;
L1:
    r0 ← φ(start : r, L1 : r1);
    x0 ← φ(start : x, L1 : x1);
    if x0 then
        r1 ← mul(r0, x0);
        x1 ← sub(x0, 1);
        goto L1;
    else
        ret r0;
}
ret fac(10);

```

$p ::= \text{proc } x(xs) \{b\} p \mid e$   
 $b ::= e \mid b; x:e \quad \cancel{+ b_1; x:\{b_2\}}$   
 $e ::= x \leftarrow \phi(gs); e$   
 $\quad \mid x \leftarrow v; e$   
 $\quad \mid x \leftarrow v(vs); e$   
 $\quad \mid \text{goto } x;$   
 $\quad \mid \text{ret } v;$   
 $\quad \mid \text{ret } v(vs);$   
 $\quad \mid \text{if } v \text{ then } e_1 \text{ else } e_2$   
 $g ::= l:v$   
 $l ::= x \mid \text{start}$   
 $v ::= x \mid c$   
 $xs ::= x, xs \mid \epsilon$   
 $vs ::= v, vs \mid \epsilon$   
 $gs ::= g, gs \mid \epsilon$   
 $x ::= \text{variable or label}$   
 $c ::= \text{constant}$

# Administrative Normal Form

- Restricted form of lambda terms
- Like SSA, arguments to functions must be atomic
- Doesn't differentiate between labels and procedures
- Used by GHC, DDC, Icicle, SML/NJ, MLton
- Also called A-Normal Form

# Administrative Normal Form

```
letrec fac (x) =  
  letrec L1 (r0, x0) =  
    if x0 then  
      let r1 = mul (r0, x0) in  
      let x1 = sub (x0, 1) in  
        L1 (r1, x1)  
    else  
      r0  
  in  
    let r = 1 in  
      L1 (r, x)  
  in  
  fac (10)
```

e ::= v  
| v(v)  
| let x = v in e  
| let x = v(vs) in e  
| letrec fs in e  
| if v then e<sub>1</sub> else e<sub>2</sub>  
f ::= x(xs) = e  
v ::= x | c  
xs ::= x, xs | ε  
vs ::= v, vs | ε  
fs ::= f; fs | ε  
x ::= variable  
c ::= constant

# Administrative Normal Form

```
letrec fac (x) =  
  letrec L1 (r0, x0) =  
    if x0 then  
      let r1 = mul (r0, x0) in  
      let x1 = sub (x0, 1) in  
        L1 (r1, x1)  
    else  
      r0  
  in  
    let r = 1 in  
      L1 (r, x)  
  in  
    fac (10)
```

e ::= v  
| v(v)  
| let x = v in e  
| let x = v(vs) in e  
| letrec fs in e  
| if v then e1 else e2  
f ::= x(xs) = e  
v ::= x | c  
xs ::= x, xs | ε  
vs ::= v, vs | ε  
fs ::= f; fs | ε  
x ::= variable  
c ::= constant

# Conditional Dead Code Elimination



# Conditional DCE in SSA

```
proc calcProfit(x, y) {
    if 0 then
        x0 ← x;
        goto L1;
    else
        r0 ← mul(x, y);
        goto L2;
L1:
    ...
L2:
    p ← φ(L1 : x1, start : r0);
    ret p;
}
```

L1:

```
x1 ← φ(start : x0, L1 : x2);
if y0 then
    x2 ← mul(x1, 2);
    y1 ← sub(y0, 1);
    goto L1;
else
    goto L2;
```

# Conditional DCE in SSA

```
proc calcProfit(x, y) {
    if 0 then
        x0 ← x;
        goto L1;
    else
        r0 ← mul(x, y);
        goto L2;
L1:
    ...
L2:
    p ← φ(L1 : x1, start : r0);
    ret p;
}
```

L1:

```
x1 ← φ(start : x0, L1 : x2);
if y0 then
    x2 ← mul(x1, 2);
    y1 ← sub(y0, 1);
    goto L1;
else
    goto L2;
```

A light blue arrow points from the end of the L1 block back to the condition 'if 0 then' in the main procedure body.

# Conditional DCE in SSA

```
proc calcProfit(x, y) {
    if 0 then
        x0 ← x;
        goto L1;
    else
        r0 ← mul(x, y);
        goto L2;
L1:
    ...
L2:
    p ← φ(L1 : x1, start : r0);
    ret p;
}
```

L1:

```
x1 ← φ(start : x0, L1 : x2);
if y0 then
    x2 ← mul(x1, 2);
    y1 ← sub(y0, 1);
    goto L1;
else
    goto L2;
```

# Conditional DCE in SSA

```
proc calcProfit(x, y) {
    if 0 then
        x0 ← x;
        goto L1;
    else
        r0 ← mul(x, y);
        goto L2;
L1:
    ...
L2:
    p ← φ(L1 : x1, start : r0);
    ret p;
}
```

L1:

```
x1 ← φ(start : x0, L1 : x2);
if y0 then
    x2 ← mul(x1, 2);
    y1 ← sub(y0, 1);
    goto L1;
else
    goto L2;
```

# Conditional DCE in SSA

```
proc calcProfit(x, y) {  
    r0 ← mul(x, y);  
    goto L2;  
L1:  
    ...  
L2:  
    p ← φ(L1 : x1, start : r0);  
    ret p;  
}
```

L1:

$x_1 \leftarrow \phi(\text{start} : x_0, L1 : x_2);$

if  $y_0$  then

$x_2 \leftarrow \text{mul}(x_1, 2);$

$y_1 \leftarrow \text{sub}(y_0, 1);$

goto L1;

else

goto L2;



Problem: **x0** doesn't exist

# Conditional DCE in SSA

```
proc calcProfit(x, y) {
    L1:
        x1 ← φ(start : x0, L1 : x2);
        if y0 then
            x2 ← mul(x1, 2);
            y1 ← sub(y0, 1);
            goto L1;
        else
            goto L2;
    L1:
        ...
    L2:
        p ← φ(L1 : x1, start : r0);
        ret p;
}
```

Problem: we never jump to L1

# Unused Code Elimination in SSA

```
proc calcProfit(x, y) {  
    r0 ← mul(x, y);  
    goto L2;  
L1:  
    ...  
L2:  
    p ← φ(L1 : x1, start : r0);  
    ret p;  
}
```

L1:

```
x1 ← φ(start : x0, L1 : x2);  
if y0 then  
    x2 ← mul(x1, 2);  
    y1 ← sub(y0, 1);  
    goto L1;  
else  
    goto L2;
```

# Unused Code Elimination in SSA

```
proc calcProfit(x, y) {  
  
    r0 ← mul(x, y);  
    goto L2;  
  
L2:  
    p ← φ(  
            start : r0);  
    ret p;  
}
```

# Redundant $\phi$ Elimination in SSA

```
proc calcProfit(x, y) {  
  
    r0 ← mul(x, y);  
    goto L2;  
  
L2:  
    p ← ϕ( start : r0);  
    ret p;  
}
```

# Redundant $\phi$ Elimination in SSA

```
proc calcProfit(x, y) {  
  
    r0 ← mul(x, y);  
    goto L2;  
  
L2:  
    p ← r0 ;  
    ret p;  
}
```

# Block Merging in SSA

```
proc calcProfit(x, y) {
```

```
    r0 ← mul(x, y);  
    goto L2;
```

L2:

```
    p ← r0 ;  
    ret p;  
}
```

# Block Merging in SSA

```
proc calcProfit(x, y) {  
    r0 ← mul(x, y);  
  
    p ← r0 ;  
    ret p;  
}
```

# Copy Propagation in SSA

```
proc calcProfit(x, y) {
```

```
    r0 ← mul(x, y);
```

```
    p ← r0 ;  
    ret p r0;  
}
```

# Copy Propagation in SSA

```
proc calcProfit(x, y) {  
    r0 ← mul(x, y);  
    ret r0;  
}
```



That escalated quickly

# Conditional DCE in ANF

```
letrec calcProfit (x, y) =
  if 0 then
    letrec loop (x0, y0) =
      if y0 then
        let x1 = mul (x0, 2)
        let y1 = sub (y0, 1)
        loop (x1, y1)
      else
        x0
    in
    loop (x, y)
  else
    mul (x, y)
in
...
```

# Conditional DCE in ANF

```
letrec calcProfit (x, y) =  
  if 0 then  
    letrec loop (x0, y0) =  
      if y0 then  
        let x1 = mul (x0, 2)  
        let y1 = sub (y0, 1)  
        loop (x1, y1)  
      else  
        x0  
    in  
    loop (x, y)  
  else  
    mul (x, y)  
in
```

...

# Conditional DCE in ANF

```
letrec calcProfit (x, y) =
```

```
    mul (x, y)
```

```
in
```

...

# Too easy!





# Inlining

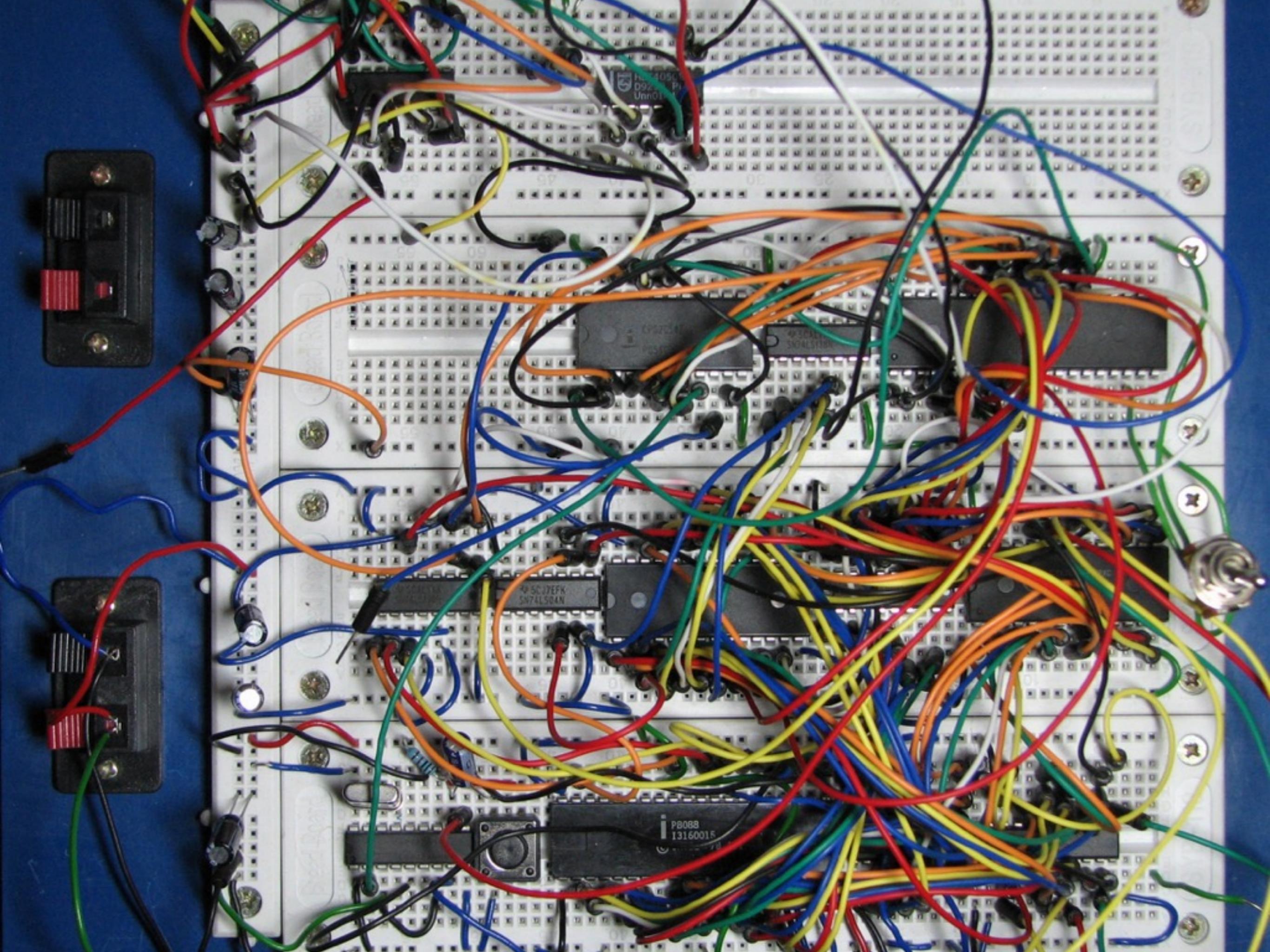
# Inlining in SSA

```
proc facOver(n) {  
    goto L1;  
L1:  
    n0 ← φ(start : n, L1 : n1);  
    a ← fac(n0);  
    b ← gt(a, n0);  
    if b then  
        ret n0;  
    else  
        n1 ← add(n0, 1);  
        goto L1;  
}
```

```
proc fac(x) {  
    r ← 1;  
    goto L4;  
L4:  
    r0 ← φ(start : r, L4 : r1);  
    x0 ← φ(start : x, L4 : x1);  
    if x0 then  
        r1 ← mul(r0, x0);  
        x1 ← sub(x0, 1);  
        goto L4;  
    else  
        ret r0;  
}  
  
ret facOver(100);
```

# Inlining in SSA

```
proc facOver(n) {  
    goto L1;  
L1:  
    n0 ← φ(start : n, L1L2 : n1);  L4:  
    x ← n0  
    goto L3;  
★L2:  
    a ← r0;  
    b ← gt(a, n0);  
    if b then  
        ret n0;  
    else  
        n1 ← add(n0, 1);  
        goto L1;  
★L3:  
    r ← 1;  
    goto L4;  
r0 ← φ(startL3 : r, L4 : r1);  
x0 ← φ(startL3 : x, L4 : x1);  
if x0 then  
    r1 ← mul(r0, x0);  
    x1 ← sub(x0, 1);  
    goto L4;  
else  
    ret r0  
    goto L2;  
}  
ret facOver(100);
```



# Inlining in ANF

```
letrec
  facOver (n) =
    letrec loop (n0) =
      let a = fac (n0)
      let b = gt (a, n0)
      if b then
        n0
      else
        let n1 = add (n0, 1)
        loop (n1)
    in
    loop (n)
in
facOver (100)
```

```
fac (x) =
letrec L1 (r0, x0) =
  if x0 then
    let r1 = mul (r0, x0)
    let x1 = sub (x0, 1)
    L1 (r1, x1)
  else
    r0
in
let r = 1
L1 (r, x)
```

# Inlining in ANF

```
letrec
  facOver (n) =
    letrec loop (n0) =
      letrec L1 ... ←————— letrec L1 (r0, x0) =
        in
          let r = 1
          let a = fac (n0) L1 (r, n0)
          let b = gt (a, n0)
          if b then
            n0
          else
            let n1 = add (n0, 1)
            loop (n1)
      in
        loop (n)
  in
    facOver (100)
```

if x<sub>0</sub> then  
let r<sub>1</sub> = mul (r<sub>0</sub>, x<sub>0</sub>)  
let x<sub>1</sub> = sub (x<sub>0</sub>, 1)  
L1 (r<sub>1</sub>, x<sub>1</sub>)  
else  
r<sub>0</sub>



# But what about all the great optimisation passes in LLVM?

- Algorithms designed to operate on SSA programs can readily be translated to operate on ANF programs
- [1] gives a formally proven (in Coq) translation from SSA to ANF
- [1] also shows how to implement Sparse Conditional Constant Propagation (SCCP) [2] on ANF
- Check out my github [3] to see a Haskell implementation of the above

1. Chakravarty, Keller, Zadarnowski. *A functional perspective on SSA optimisation algorithms* (2003)
2. Wegman, Zadeck. *Constant Propagation with Conditional Branches* (1991)
3. <https://github.com/jystic/ssa-anf>

“In optimizing compilers, data structure choices directly influence the power and efficiency of practical program optimization. A poor choice of data structure can inhibit optimization or slow compilation to the point that advanced optimization features become undesirable.”

– Cytron, Ferrante, Rosen, Wegman & Zadeck 1991

So use ANF!

# Further Reading

- Flanagan, Sabry, Duba, Felleisen. *Retrospective: The essence of compiling with continuations* (2010)
- Chakravarty, Keller, Zadarnowski. *A functional perspective on SSA optimisation algorithms* (2003)
- Appel. *SSA is functional programming* (1998)
- Kelsey. A correspondence between *Continuation Passing Style and Static Single Assignment Form* (1995)
- Flanagan, Sabry, Duba, Felleisen. *The essence of compiling with continuations* (1993)
- Cytron, Ferrante, Rosen, Wegman, Zadeck. *Efficiently computing static single assignment form and the control dependence graph* (1991)
- <https://github.com/jystic/ssa-anf>